ANALYSIS OF DYNAMIC VOLTAGE RESTORER WITH PI AND FUZZY LOGIC BASED CONTROLLER FOR VOLTAGE SAG MITIGATION IN DISTRIBUTION SYSTEM

ABSTRACT

The objective of this paper is to the analysis of dynamic voltage restorer with PI and fuzzy logic controllers for voltage Sag mitigation in the distribution system. Distribution system needs to be protected from voltage sags, dips & swells that adversely affect the reliability & quality of power supply at the utility end. These problems can be mitigated with voltage injection method using custom power device, Dynamic Voltage Restorer (DVR). Proportional Integral (PI) Controller and Fuzzy Logic (FL) Controller are the two controllers introduced in this paper for mitigation of voltage sag during abnormal conditions. The proposed DVR employs the classical Fourier Transform (FT) for sag/swell detection and quantification and a Fuzzy Logic based feedback controller which utilizes the error signal (difference between the reference voltage and actual measured load voltage) to control the triggering of the switches of an inverter using a Sinusoidal Pulse Width Modulation (SPWM) scheme. The proposed DVR utilizes the energy from available supply line feeders through a rectifier to feed the inverter. MATLAB/SIMULINK platform is used for the evaluation of the proposed DVR in the distribution system. Overall the DVR is improving the voltage quality as well as the reactive power demand during the uncharacteristic condition.

Keywords:
Dynamic voltage Restorer, Voltage sag, THD, PI with Fuzzy Logic Controller, Pulse Width Modulation.

Name of the Author:

Karthik K¹,
D. Narmitha²,
Pindiboyina Aruna³

Assistant Professor, Dept. of EEE, School of Engineering and Technology, SPMVV, Tirupathi. (INDIA)

Citation of the Article

I. INTRODUCTION

Two of the main problems in the field of power quality are voltage sag and instantaneous power loss [8]. In addition, voltage sag has two main parameters including magnitude and time duration. Typically, DVR voltage injection method is used to compensate the difference between voltage when sag occurs and when before sag occurs, using AC voltage in series. Another method is to inject voltage in phase with supply voltage when sag occurs [2]. The advantage of both methods is that it uses economical energy storage, yet it has the disadvantage of the occurrence of phase shift.

The conventional fuzzy logic controller can reduce the time needs; however, this controller needs many membership functions. Some researchers have been done to decrease the number of membership functions. High quality in the power supply is needed since failures due to such disturbances usually have a high impact on production costs. There are a number of methods to overcome voltage sags. One approach is to use Dynamic Voltage Restorers with energy storage. The DVR is a power electronics device that is able to compensate voltage sags on critical loads dynamically. By injecting an appropriate voltage, the DVR restores a voltage waveform and ensures constant load voltage. The DVR consists of Voltage Source Converter (VSC), injection transformers, passive filters, and energy storage (lead acid battery) [4]. The Dynamic Voltage Restorer (DVR) with the lead acid battery is an attractive way to provide excellent dynamic voltage compensation capability as well as being economical when compared to shunt-connected devices [1]. The DVR is a custom power device that is connected in series with the distribution system. The DVR employs IGBTs to maintain the voltage applied to the load by injecting three-phase output voltages with small magnitude, phase and frequency can be controlled. Control unit is the heart of the DVR where its main function is to detect the presence of voltage sags in the system, calculating the required compensating voltage for the DVR and generate the reference voltage for PWM generator to trigger on the PWM inverter. The components of the control system unit are dq0-transformation, Phase-lock-loop (PLL) and the PI with FL Controller. PI Controller is a feedback controller which drives the plant to be controlled with a weighted sum of the error (the difference between output and desired set-point) and the integral of that value.

A new fuzzy logic (FL) method has been applied to custom power devices, especially for active power filters [3]. The operation of DVR is similar to that of active power filters in that both compensators must respond very fast to the request from abruptly changing reference signals. In the literature, FL control of DVR based on dq Synchronous Reference Frame (SRF). In three-phase supply voltages are transformed into d and q coordinates. The reference values for $V_d$ and $V_q$ are compared with these transformed values and then voltage errors are obtained. FL controllers evaluating linguistic rules process these errors. Resulting outputs are retransformed into the three-phase domain and compared with a carrier signal to generate PWM inverter signals. This paper presents the modeling and simulation of a PI with FLC-based DVR under voltage sag phenomena. In this case, the PI with the fuzzy logic controller has been incorporated instead of conventional another controller. The simulation tool is the MATLAB/Simulink Power System Block set (PSB). The capability of DVR to mitigate the voltage sag is demonstrated by MATLAB simulation. The addition of PI with fuzzy logic control to gives added advantage of faster response as compared to the conventional one.

II. POWER QUALITY RELATED PROBLEMS

Power quality means the fitness of electrical power and its stabilized disposition to power consumer device. PQ problem is defined as any problem manifested in voltage, current or a frequency deviation that leads to the failure or misoperation of consumer equipment. Power quality is not a single unit measurement it is a collection of several types which includes Capacitor switching, lightning surge (Transient), Interruptions, Sags/Swells (Disturbance), Harmonics, Flicker, Voltage regulation, Reliability, Power factor (Steady-state). There are several types of power quality problems that a customer may encounter and may classify according to or depending on how the voltage waveform is being distorted. There are transients, short duration of variations (sags, swells, and interruption), long duration variations (sustained interruptions, under voltages, over voltages), voltage imbalance, waveform distortion (dc offset, harmonics, inter-harmonics, notching, and noise), voltage fluctuations and power frequency variations.

The IEEE standards of voltage reduction are shown in Fig.1. Voltage sag is a reduction of RMS voltage between 0.1 p.u. and 0.9 p.u. and lasting between 0.5 cycles to 1 minute. Voltage sag is mostly caused by system fault and last for a duration ranging from 3 cycles to 30 cycles depending on the fault clearing time [6]. A voltage swell is defined as a rise in RMS voltage which is between 1.1 p.u and 1.8p.u for period stuck between 0.5 cycles to 1 minute. A voltage swell is characterized by its magnitude (RMS) and duration.

![Fig. 1 Voltage reduction standard of IEEE](image)

In general, there are two come within reach of followed to alleviate the tribulations associated with power quality. The first approach is called load training, which guarantees that the equipment is less perceptive to power turbulence permitting the operation still below significant voltage deformation and the second approach is to mount line conditioning schemes that suppress or neutralizes the power schemes turbulences. The procession conditioning system or convenience side solutions will participate a major role in improving the inherent supply quality; some of the effective and economic measures can be identified which are as follows: Lightening and Surge Arresters, Thyristor Based Static Switches, Energy Storage Systems, Harmonic Filters etc.

III. DYNAMIC VOLTAGE RESTORER

The major objectives are to increase the capacity utilization of distribution feeders (by minimizing the RMS values of the line currents for a specified power demand), reduce the losses and improve power quality at the load bus. The major assumption was to neglect the variations in the source voltages. This essentially implies that the dynamics of the source voltage is much slower than the load dynamics [7].
The voltage source converter is typically one or more converters connected in series to provide the required voltage rating. The DVR can inject a (fundamental frequency) voltage in each phase of required magnitude and phase. The DVR has two operating modes [5].

- Standby (also termed as Short Circuit Operation (SCO) mode) where the voltage injected has zero magnitude.
- Boost (when the DVR injects a required voltage of appropriate magnitude and phase to restore the pre-fault load bus voltage).

The basic structure of DVR is shown in Fig. 2. It consists of the following main components whose description is given below:

A. Voltage Source Inverter

It forms the building block of compensating device. It performs the power conversion process from DC to AC. VSI consists of fully controlled semiconductor power switches to form a single phase or three-phase topologies. For medium power inverters, IGBT’s are used and GTO’s or IGCT’s due to compact size & fast response for high power inverters are employed. The single phase VSI topology encompasses low-range power applications and medium to high power applications are covered by the three phase topology.

B. Series Injection Transformer

It provides electrical isolation & voltage boost to the system. In a 3-phase system, either 3 single phase units of isolating transformer or 3-phase isolating transformer can be employed for the purpose of voltage injection. The proposed system uses 3 single phase units of isolating transformer with unity turns ratio.

C. Filters

These are electronic circuits comprising of a combination of passive elements; resistors, inductors & capacitor. LC type of filters corrects the harmonic output from VSI to provide compensation in the required phase of the 3 phase system boosted by DVR.

D. Energy Storage

This is required to provide active power to the load during deep voltage sags. Lead-acid batteries, flywheel or SMES can be used for energy storage. It is also possible to provide the required power on the DC side of the VSC by an auxiliary bridge converter that is fed from an auxiliary AC supply.

IV. CONTROL TECHNIQUES FOR DVR

The fundamental roles of a controller in a DVR are to detect the voltage sag occurrence in the system; calculate the compensating voltage, to generate trigger pulses of PWM inverter and stop triggering when the occurrence has passed. The basic flow chart for the operation of DVR is shown in Fig.3. Using RMS value calculation of the voltage to analyze the sags does not give a fast and accurate result. In this study, the dq transformations or parks transformations is used in voltage calculation. The dqo transformation is a transformation of coordinates from the three phase stationary coordinate system to the dq rotating coordinate system. This doph method gives the information of the depth (d) and phase shift (q) of voltage sag with start and end time.

\[
V_o = \frac{1}{3} (V_a + V_b + V_c) \quad (1)
\]

\[
V_d = \frac{2}{3} \left( V_a \sin \omega t + V_b \sin (\omega t - \frac{2\pi}{3}) + V_c \sin (\omega t + \frac{2\pi}{3}) \right) \quad (2)
\]

\[
V_q = \frac{2}{3} \left( V_a \cos \omega t + V_b \cos (\omega t - \frac{2\pi}{3}) + V_c \cos (\omega t + \frac{2\pi}{3}) \right) \quad (3)
\]

After conversion, the three-phase voltage \( V_a, V_b, V_c \) become two constant voltages \( V_d \) and \( V_q \) and now they are easily controlled. In this paper, two control techniques have been proposed which are proportional-integral (PI) controller and fuzzy logic (FL) controller.

A. Proportional-Integral-Controller

PI Controller is a feedback controller which drives the plant to be controlled with a weighted sum of the error and the integral of that value. The proportional response can be adjusted by multiplying the error by constant KP, called proportional gain. The contribution from integral term is proportional to both the magnitude of error and duration of error. The error is first multiplied by the integral Gain, Ki and then was integrated to give an accumulated offset that has been corrected previously.

B. Fuzzy Logic Controller

Fuzzy logic (FL) controller is one of the most successful operations of fuzzy set theory, its major features are the use of linguistic variables rather than numerical variables. This control technique relies on human capability to understand the behavior of the system and is based on quality control rules [9]. Fuzzy Logic provides a simple way to arrive at a definite conclusion based upon vague, ambiguous, imprecise, noisy, or missing input information. The basic functions of PLC are listed in following four steps [10].
- A Fuzzyfication interface which converts input data into suitable linguistic values.
- A Knowledge Base which consists of a database with the necessary linguistic definitions and control rule set.
- A Decision Making Logic which, simulating a human decision process, infers the fuzzy control action from the knowledge of the control rules and the linguistic variable definitions and
- A De-fuzzyfication interface which yields a non-fuzzy control action from an inferred fuzzy control action.

In the proposed system, two FL controller blocks are used for error signal-d and error signal-q. Error and Change in Error are the inputs to the fuzzy controller and are shown in Fig. 4 to Fig. 6.

In the decision-making process, there is a rule base that links between input (error signal) and output signal. Table 1 shows the rule base used in this FL controller [11].

<table>
<thead>
<tr>
<th>DE/E</th>
<th>N</th>
<th>Z</th>
<th>PS</th>
<th>PFS</th>
<th>PA</th>
<th>PFB</th>
<th>PB</th>
<th>PVB</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>N</td>
<td>Z</td>
<td>PS1</td>
<td>PFS1</td>
<td>PA1</td>
<td>PFB1</td>
<td>PFB2</td>
<td>PVB</td>
</tr>
<tr>
<td>P</td>
<td>N</td>
<td>Z</td>
<td>PS2</td>
<td>PFS2</td>
<td>PA2</td>
<td>PFB2</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

V. SIMULATION RESULTS AND DISCUSSION

In order to understand the performance of the DVR along with control, a simple distribution network as shown in Fig. 7 is implemented. There are different fault conditions like normal system, single line to ground fault, double line to ground fault, three phase fault, and voltage sag simulated using MATLAB/SIMULINK software. PI with a fuzzy logic controller is used for the control purpose. The DVR system connected to the distribution system using a booster transformer.
Fig. 7 Simulink Model of DVR Test System

In this system different fault conditions like a normal system, single line to ground fault, double line to ground fault, three phase fault and voltage sag with a feeder for the duration of 0.25s to 0.35s with fault resistance is 20 ohms and the ground resistance is 0.001 ohms. The output voltage of the proposed system is shown in Fig. 8 to Fig. 11 under different conditions.

Fig. 8 Normal system; (a) Supply voltage, (b) Injection voltage, and (c) Load voltage

Fig. 9 Single Line to ground fault; (a) Supply voltage, (b) Injection voltage, and (c) Load voltage
Fig. 10 Double Line to ground fault; (a) Supply voltage, (b) Injection voltage, and (c) Load voltage

Fig. 11 Three phase fault; (a) Supply voltage, (b) Injection voltage, and (c) Load voltage

The THD analysis of the proposed system is shown in Fig.12 and the corresponding THD values are listed in Table. 2 under different conditions.

**Table.2 Comparison of THD**

<table>
<thead>
<tr>
<th>S.no.</th>
<th>Condition</th>
<th>THD (%)</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>Normal system</td>
<td>0.45</td>
</tr>
<tr>
<td>2</td>
<td>Single Line to Ground Fault</td>
<td>0.77</td>
</tr>
<tr>
<td>3</td>
<td>Double Line to Ground Fault</td>
<td>0.77</td>
</tr>
<tr>
<td>4</td>
<td>Three Phase Fault</td>
<td>0.78</td>
</tr>
</tbody>
</table>
VI. CONCLUSION

The analysis of DVR with PI and a Fuzzy logic controller for voltage restoration has been presented in this paper. A controller utilizes the error signal which is actually the difference between the reference signal and the actual signal. Voltage source converter was implemented with the help of pulse width modulation. It is fast and simple and finally, a Fuzzy Logic based feedback controller is used to control the voltage injection of the proposed DVR system in case of voltage disturbances. The proposed DVR utilizes energy drawn from the supply line source during normal operation and stores in capacitors and which is converted to an adjustable three phase AC voltage suitable for mitigation of voltage sags. The THD values of the proposed system are listed and compared between the different fault conditions. The main advantages of the proposed DVR are simple and efficient adaptive control and fast response.

REFERENCES


*****